

REC'D	23	JAN	2004	
WIPO		F	CT	

## Intyg Certificate

Härmed intygas att bifogade kopior överensstämmer med de handlingar som ursprungligen ingivits till Patent- och registreringsverket i nedannämnda ansökan.

This is to certify that the annexed is a true copy of the documents as originally filed with the Patent- and Registration Office in connection with the following patent application.

- (71) Sökande Danaher Motion Stockholm AB, Stockholm SE Applicant (s)
- (21) Patentansökningsnummer 0203835-4 Patent application number
- (86) Ingivningsdatum

  Date of filing

2002-12-23

Stockholm, 2004-01-15.

För Patent- och registreringsverket For the Patent- and Registration Office

Marita Öun

Avgift Fee

PRIORITY
DOCUMENT
SUBMITTED OR TRANSMITTED IN
COMPLIANCE WITH RULE 17.1(a) OR (b)

## Inverter type motor drive unit.

The invention relates to an electric motor drive unit of the inverter type for feeding AC electric power of variable current and frequency to an electric motor in relation to the actual operation condition of the motor, wherein the drive unit comprises an electronic control section and a power converting and output section connected via DC terminals at one end to a DC source and via AC terminals at its other end to the motor.

In order to easily adapt the drive unit to different power output demands, i.e. motors of different size, the power converting and output section comprises one or more identical power modules connected in parallel, such that a suitable number of power modules is chosen for a certain motor size.

A problem concerned with a modular type of power converting and output section is to obtain a necessarily high accuracy as to an even and simultaneous DC current supply to all modules, no matter their physical positions in relation to the DC input terminals as well as to each other.

The main object of the invention is to provide an improved inverter type motor drive unit of the above mentioned type wherein the DC current supply to the power module or modules is carried out symmetrically and at a very low impedance.

Another object of the invention is to provide an inverter type drive unit of the above recited type having a simple and easily assembled design.

A further object of the invention is to provide an inverter type drive unit of the above mentioned type wherein occurring heat resulted from current losses are effectively transferred to a cooling structure.

Further characteristic features and advantages of the invention will appear from the following specification wherein a preferred embodiment of the invention is described in detail with reference to the accompanying drawings.

In the drawings

Fig.1 shows an end view of the motor drive unit according to the invention.

Fig. 2 shows a top view of a motor drive unit in Fig. 1.

Fig. 3 shows a side view of the motor drive unit in Fig. 1.

Fig. 4 shows on a larger scale a detail view of the motor drive unit in Fig. 1.

Fig. 5 shows a perspective view of the stacked power module connection sheets.

Fig. 6 shows an exploded view of the connection sheets and insulating sheets and guide elements.

The inverter type motor drive unit illustrated in the drawing figures, which is suitable for use in for instance battery powered trucks, comprises a mounting and cooling structure 10 of aluminium alloy on which is carried three identical power modules 11a-c. These power modules 11a-c form a power converting and output section. The three power modules 11 a-c are located side by side on the cooling structure 10 and are intended to deliver AC power to a motor of a certain size. Each power module 11a-c forms a complete 3-phase output stage.

The drive unit is easily adaptable to smaller or bigger motors with smaller or bigger power demands by altering the number of power modules. In case of a bigger motor the number of modules are increased in such a way that one or

more identical modules are added in a parallel side-by-side fashion in a multiplying direction A on the cooling structure 10. See arrow in Figs. 1 and 2. In case of a smaller motor one or two power modules are left out. Accordingly, the power modules lla-c are multiplied by a suitable number and are arranged in parallel to meet the power demand of an actual motor size. The specific side-by-side location of the power modules lla-c is important for obtaining an advantageous current distribution to all power modules lla-c as described below.

Motor types suitable to be driven by this drive unit are asynchronous motors, permanent magnet motors and reluctance motors.

Each power module 11 a-c comprises a conductive substrate 12 a-c which carries a number of power switches (not illustrated) for converting an input DC current to a three-phase AC output current. For each power module 11 a-c there is a capacitor bank 13 a-c which is firmly mounted on the cooling structure 10 for heat transfer. The substrates 12 a-c are also clamped into a heat transferring contact with the cooling structure 10 by means of retaining devices 14. Each retaining 14 device consists of a tubular distance piece 15 and a clamping screw 16, wherein the clamping screw 16 extends through the tubular distance piece 15 and is threaded into the cooling structure 10. See Fig. 4. The distance piece 15 is made of a metallic material for conducting electric current as well as heat between the conductive sheets 20,21,27a-c and the power modules 11a-c.

A substrate arrangement of this type is previously described in US Patent No. 5,715,141.

For connecting the power modules 11 a-c to the DC input there are provided two electrically conductive layers in the form of metal sheets 20, 21. These sheets 20,21 have a

4

size covering a surface area occupied physically by all three power modules 11 a-c as, including the capacitor banks 13a-c which are covered via Z-shaped portions 22a,b of the sheets 20,21.

Between the two sheets 20,21 there is an insulating layer in the form a non-conducting sheet 19. One of the conductive sheets 20 carries a connection pillar 25 for the positive DC pole, whereas the other conductive sheet 21 carries another connection pillar 26 for the negative DC . pole. By specifically shaped connection portions 23a-c and 24a-c (not described in further detail) on the Z-shaped portions 22a,b there is obtained a proper connection of one of the sheets 20 to one of the poles of each capacitor bank 13a-c and a connection of the other sheet 21 to the other pole of each capacitor bank 13a-c. A third conductive layer in the form of three parallel metal sheets 27a-c is separated from the other sheets by an insulating sheet 30 and connected to the power modules 11a-c. These parallel sheets 27a-c are provided with connection pillars 32,33,34 for delivering the 3-phase output AC current to the motor to be driven. See Fig. 6.

For accomplishing a simple, fast and correct mounting of the conductive sheets 20,21 and 27 a-c on the power module substrates 12a-c there are provided three guide elements 36 a-c of an insulating material, one for each power module. As can be observed in Fig. 4, each one of the guide elements 36a-c is provided with stepped downwardly directed stud portions 37a-c which are intended to be received with friction in apertures of matching sizes in all conductive and insulating sheets. This means that all the conductive and non-conductive sheets can be pre-assembled by means of these guide elements 36a-c to a stack and mounted as a sub-assembly on the substrates 12 a-c and the cooling structure 10. See Fig. 5. This means a substantially improved assembling technique.

By having the DC connection to the power modules via the large area conductive sheets 20,21 there is obtained an even and simultaneous DC current supply to all power modules 11 a-c, and the DC current is supplied to the power modules 11 a-c is symmetric and takes place at a very low impedance, no matter the distance to the connection pillars 25,26. It also means a symmetric current path between each parallel power module 11 a-c and corresponding capacitor bank 13 a-c.

The drive unit further comprises an electronic control section 40 which comprises a circuit board 41 with electronic components (not illustrated) and which is mounted above the power modules 11a-c by means of connector pin units 42. The control section circuit board 40 is connected to the power modules 11a-c via two elongate circuit board type signal buses 44a,b extending in the multiplying direction A of the drive unit. This type of signal bus has a low resistance and a low impedance for obtaining an even and simultaneous communication between the control section 40 and the power modules 11a-c.

As illustrated in Fig. 4, the retaining devices 14 have distance pieces 15 of different length for obtaining an electrical as well as thermal contact with the different conducting sheets 20,21,27a-c disposed at different distances from the substrates 12 a-c. Apart from retaining the stack of sheets properly in relation to the power module substrates 12 a-c the distance pieces 15 are effective in conducting electric current between the sheets 20,21,27a-c and the substrates 12a-c as well as transferring heat developed in the sheets. The retaining devices 14 also clamp the substrates 12a-c into a heat transferring contact with the cooling structure 10.

The modular drive unit design according to the invention means a simplification in adapting the output capacity to motors of different sizes. This means that a suitable number of identical power modules 11a-c are chosen to meet the power demand of the actual motor size. The conductive as well as the non-conductive sheets, however, have to be adapted in size to the actual number of power modules. Also the signal buses 44a,b have to be adapted in length to the actual number of power modules and the total size of the surface area covered by the power modules 11a-c.

In its practical use, the drive unit is provided with a non-illustrated protective hood, wherein the DC terminal pillars 25,26 and the AC output pillars 32,33,34 extend out through the hood for cable connections.

## Claims.

- 1. Inverter type motor drive unit for feeding AC electric power of variable parameters to an electric motor, comprising an electronic control section (40), a power converting and output section controlled by the control section (40), two input terminals (25,26) for connection to a DC power source, and three output terminals (32,33,34) for delivering a 3-phase AC power to an electric motor, c h a r a c t e r i z e d in that the power converting and output section comprises
- one or more identical power modules (11a-c) each comprising a complete 3-phase output stage,
- said power module or modules (11a-c) are multiplied by a suitable number and interconnected in parallel to meet the power demand of the actual motor size,
- said power module or modules (11a-c) are mounted side by side in a multiplying direction (A) on a cooling structure (10), thereby covering a certain surface area substantially corresponding in size to the surface area covered by the actual number of power modules (11a-c),
- said power module or modules (11a-c) are connected to said DC input terminals (25,26) and said AC output terminals (32,33,34) via conductive layers (20,21,27a-c) which are electrically insulated from each other and extend substantially in parallel with said cooling structure (10) and covering substantially all of said certain surface area.
- 2. Motor drive unit according to claim 1, wherein one of said conductive layer (27a-c) is divided into three separate leads (27a-c) extending in parallel to each other across said power modules (11a-c) in said multiplying direction (A) and connecting said power module or modules (11a-c) in parallel to said AC output terminals (32,33,34).

- PRV 00-12-20 M
- Motor drive unit according to claim 1 or 2, wherein all of said conductive layers (20,21,27a-c) comprise separate metal sheets, and a number of retaining devices (14) are arranged both to connect said metal sheets (20,21,27a-c) to said power module or modules (11a-c) and to clamp said power module or modules (11a-c) into a physical heat transferring contact with said cooling structure (10).
- 4. Motor drive unit according to claim 3, wherein two of said metal sheets (20,21) are connected to said DC input terminals (25,26), and said power module or modules (11a-c) are connected to capacitor banks (13a-c) via said two metal sheets (20,21).
- Motor drive unit according to claim 3, wherein each one of said retaining devices (14) comprises a clamping member (16) and a distance piece (15) for locating each metal sheet (20,21,27a-c) at a specific distance from said power modules (11a-c), said distance pieces (15) are electrically conductive and serve to establish an electrical as well as thermal contact between said metal sheets (20,21,27a-c) and said power modules (11a-c).
  - 6. Motor drive unit according to claim 5, wherein each one of said distance pieces (15) comprises a metallic tube element, and each one of said clamping members (16) comprises a screw extending axially through said tube element (15).
  - Motor drive unit according to anyone of claims 3-6, wherein the control section (40) comprises a circuit board (41) supported by at least one of said power module or modules (11a-c) in a parallel but spaced disposition relative to said metal sheets (20,21,27a-c) via contact devices (42) extending through apertures in said metal sheets (20,21,27a-c).

- 8. Motor drive unit according to anyone of claims 3 4, wherein said conductive metal sheets (20,21,27a-c) are insulated relative to each other by separate insulating sheets (19,30) of a non-conductive material sandwiched between said metal sheets (20,21,27a-c), and said metal sheets (20,21,27a-c) and said insulating sheets (19,30) are arranged and fixed in a stack by said clamping members (16) and said distance pieces (15).
- 9. Motor drive unit according to claim 8, wherein one or more guide elements (36a-c) of an insulating material are provided with stud portions (37a-c) which penetrate through openings in said metal sheets (20,21,27a-c) as well as said insulating sheets (19,30) to, thereby, locate said metal sheets (20,21,27a-c) and said insulating sheets (19,30) relative to each other prior to said metal sheets (20,21,27a-c) and said insulating sheets (19,30) being finally fixed by said clamping members (16) and said distance pieces (15) at mounting of said stack on said cooling structure (10).
- 10. Motor drive unit according to claim 1 or 2, wherein said conductive layers (20,21,27a-c) comprise separate metal sheets (20,21,27a-c), and said DC input terminals (25,26) and said AC output terminals (32,33,34) are located at opposite ends of said metal sheets (20,21,27a-c) in relation to said multiplying direction (A).
- 11. Motor drive unit according to anyone of claims 1-7, wherein a signal bus means (44a,b) extends across said power module or modules (11a-c) in said multiplying direction (A) and is arranged to connect said control section (40) to each one of said power module or modules (11a-c) and communicating signals between said control section (40) and said power module or modules (11a-c).

12. Motor drive unit according to claim 11, wherein said signal bus means (44a,b) comprises at least one circuit board (44a,b).

## Abstract

An inverter type drive unit for feeding AC electric power of variable parameters to an electric motor comprises an electronic control section (40), a power converting and an output section comprising one or more identical power modules (11a-c), each forming a complete 3-phase output stage and arranged in a side-by-side disposition in a multiplying direction (A) and clamped by means of retaining devices (14a-c) to a cooling structure (10), wherein the power modules (11a-c) are connected in parallel to DC input terminals (25,26) and to AC output terminals (32,33,34) via conductive sheets (20,21,27a-c), whereof the DC connected sheets (20,21) cover substantially the entire physical surface area covered by the power modules (11a-c) so as to accomplish an even, simultaneous and low impedance DC current supply to all power modules (11a-c).

FIG 1

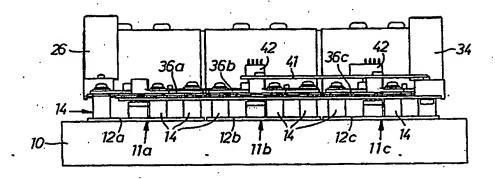


FIG 2

